

l114_sin_cos

(TMbw1f3xzmawpdjVnHsdcT1zeWUcGuHurce)

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Let $k1_relset_1 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $k1_numbers : \iota$ be given. Let $k2_partfun1 : \iota \Rightarrow \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $k29_sin_cos : \iota$ be given. Let $k1_rcomp_1 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $k6_numbers : \iota$ be given. Let $np_1 : \iota$ be given. Let $v1_xreal_0 : \iota \Rightarrow o$ be given. Let $k1_seq_1 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $r1_tarski : \iota \Rightarrow \iota \Rightarrow o$ be given. Let $k2_rcomp_1 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $v1_relat_1 : \iota \Rightarrow o$ be given. Let $k9_xtuple_0 : \iota \Rightarrow \iota$ be given. Let $k5_relat_1 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $k3_xboole_0 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $v1_funct_1 : \iota \Rightarrow o$ be given. Let $k1_funct_1 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $m1_subset_1 : \iota \Rightarrow \iota \Rightarrow o$ be given. Let $k1_zfmisc_1 : \iota \Rightarrow \iota$ be given. Let $k2_zfmisc_1 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $v3_valued_0 : \iota \Rightarrow o$ be given. Let $v4_relat_1 : \iota \Rightarrow \iota \Rightarrow o$ be given. Let $v3_membered : \iota \Rightarrow o$ be given. Let $v5_relat_1 : \iota \Rightarrow \iota \Rightarrow o$ be given. Assume the following.

$$(r1_tarski (k1_rcomp_1 k6_numbers np_1) (k1_relset_1 k1_numbers k29_sin_cos)) \wedge (r1_tarski (k2_rcomp_1 k6_numbers np_1) (k1_relset_1 k1_numbers k29_sin_cos)) \quad (1)$$

Assume the following.

$$\forall X0. \forall X1. (v1_relat_1 X1) \Rightarrow (k9_xtuple_0 (k5_relat_1 X1 X0) = k3_xboole_0 (k9_xtuple_0 X1) X0) \quad (2)$$

Assume the following.

$$\forall X0. \forall X1. \forall X2. ((v1_relat_1 X2) \wedge (v1_funct_1 X2)) \Rightarrow ((X0 \in k9_xtuple_0 (k5_relat_1 X2 X1)) \Rightarrow (k1_funct_1 (k5_relat_1 X2 X1) X0 = k1_funct_1 X2 X0)) \quad (3)$$

Assume the following.

$$\forall X0. \forall X1. (r1_tarski X0 X1) \Rightarrow (k3_xboole_0 X0 X1 = X0) \quad (4)$$

Assume the following.

$$\forall X0.\forall X1.\forall X2.\forall X3.((v1_funct_1 X2)\wedge (m1_subset_1 X2 (k1_zfmisc_1 (k2_zfmisc_1 X0 X1))))\Rightarrow(k2_partfun1 X0 X1 X2 X3 = k5_relat_1 X2 X3) \quad (5)$$

Assume the following.

$$\forall X0.\forall X1.((v1_relat_1 X0)\wedge((v1_funct_1 X0)\wedge(v3_valued_0 X0)))\Rightarrow(k1_seq_1 X0 X1 = k1_funct_1 X0 X1) \quad (6)$$

Assume the following.

$$\forall X0.\forall X1.((v1_relat_1 X1)\wedge(v4_relat_1 X1 X0))\Rightarrow(k1_relset_1 X0 X1 = k9_xtuple_0 X1) \quad (7)$$

Assume the following.

$$v3_membered k1_numbers \quad (8)$$

Assume the following.

$$\forall X0.\forall X1.\forall X2.\forall X3.((v1_funct_1 X2)\wedge (m1_subset_1 X2 (k1_zfmisc_1 (k2_zfmisc_1 X0 X1))))\Rightarrow((v1_funct_1 (k2_partfun1 X0 X1 X2 X3))\wedge(m1_subset_1 (k2_partfun1 X0 X1 X2 X3) (k1_zfmisc_1 (k2_zfmisc_1 X0 X1)))) \quad (9)$$

Assume the following.

$$(v1_funct_1 k29_sin_cos)\wedge(m1_subset_1 k29_sin_cos (k1_zfmisc_1 (k2_zfmisc_1 k1_numbers k1_numbers))) \quad (10)$$

Assume the following.

$$\forall X0.\forall X1.k3_xboole_0 X0 X1 = k3_xboole_0 X1 X0 \quad (11)$$

Assume the following.

$$\forall X0.\forall X1.\forall X2.(m1_subset_1 X2 (k1_zfmisc_1 (k2_zfmisc_1 X0 X1)))\Rightarrow((v4_relat_1 X2 X0)\wedge(v5_relat_1 X2 X1)) \quad (12)$$

Assume the following.

$$\forall X0.\forall X1.\forall X2.(m1_subset_1 X2 (k1_zfmisc_1 (k2_zfmisc_1 X0 X1)))\Rightarrow(v1_relat_1 X2) \quad (13)$$

Assume the following.

$$\forall X0.\forall X1.(v3_membered X1)\Rightarrow(\forall X2.(m1_subset_1 X2 (k1_zfmisc_1 (k2_zfmisc_1 X0 X1)))\Rightarrow(v3_valued_0 X2)) \quad (14)$$

Theorem 1

$$\begin{aligned} & (k1_relset_1 \ k1_numbers \ (k2_partfun1 \ k1_numbers \ k1_numbers \ k29_sin_cos \\ & \quad (k1_rcomp_1 \ k6_numbers \ np_1)) = k1_rcomp_1 \ k6_numbers \ np_1) \wedge \\ & \quad (\forall X0. (v1_xreal_0 \ X0) \Rightarrow ((X0 \in k1_rcomp_1 \ k6_numbers \ np_1) \Rightarrow \\ & \quad (k1_seq_1 \ (k2_partfun1 \ k1_numbers \ k1_numbers \ k29_sin_cos \ (k1_rcomp_1 \\ & \quad \quad k6_numbers \ np_1)) \ X0 = k1_seq_1 \ k29_sin_cos \ X0))) \end{aligned}$$