

t118_glib_001

(TMZJvPQ9JPGnknx8dySB21ohBYB2KgY9VwUq)

October 27, 2020

Let $v1_relat_1 : \iota \Rightarrow o$ be given. Let $v4_relat_1 : \iota \Rightarrow \iota \Rightarrow o$ be given. Let $k5_numbers : \iota$ be given. Let $v1_funct_1 : \iota \Rightarrow o$ be given. Let $v1_finset_1 : \iota \Rightarrow o$ be given. Let $v1_glib_000 : \iota \Rightarrow o$ be given. Let $m3_glib_001 : \iota \Rightarrow \iota \Rightarrow o$ be given. Let $v1_glib_001 : \iota \Rightarrow \iota \Rightarrow o$ be given. Let $k1_funct_1 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $np_1 : \iota$ be given. Let $k3_finseq_1 : \iota \Rightarrow \iota$ be given. Let $k4_glib_001 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Let $k3_glib_001 : \iota \Rightarrow \iota \Rightarrow \iota$ be given. Assume the following.

$$\begin{aligned} \forall X0.((v1_relat_1 X0) \wedge ((v4_relat_1 X0 k5_numbers) \wedge ((v1_funct_1 \\ X0) \wedge ((v1_finset_1 X0) \wedge (v1_glib_000 X0)))))) \Rightarrow (\forall X1.(m3_glib_001 \\ X1 X0) \Rightarrow (k4_glib_001 X0 X1 = k1_funct_1 X1 (k3_finseq_1 X1))) \end{aligned} \quad (1)$$

Assume the following.

$$\begin{aligned} \forall X0.((v1_relat_1 X0) \wedge ((v4_relat_1 X0 k5_numbers) \wedge ((v1_funct_1 \\ X0) \wedge ((v1_finset_1 X0) \wedge (v1_glib_000 X0)))))) \Rightarrow (\forall X1.(m3_glib_001 \\ X1 X0) \Rightarrow (k3_glib_001 X0 X1 = k1_funct_1 X1 np_1)) \end{aligned} \quad (2)$$

Assume the following.

$$\begin{aligned} \forall X0.((v1_relat_1 X0) \wedge ((v4_relat_1 X0 k5_numbers) \wedge ((v1_funct_1 \\ X0) \wedge ((v1_finset_1 X0) \wedge (v1_glib_000 X0)))))) \Rightarrow (\forall X1.(m3_glib_001 \\ X1 X0) \Rightarrow ((v1_glib_001 X1 X0) \Leftrightarrow (k3_glib_001 X0 X1 = k4_glib_001 X0 \\ X1))) \end{aligned} \quad (3)$$

Theorem 1

$$\begin{aligned} \forall X0.((v1_relat_1 X0) \wedge ((v4_relat_1 X0 k5_numbers) \wedge ((v1_funct_1 \\ X0) \wedge ((v1_finset_1 X0) \wedge (v1_glib_000 X0)))))) \Rightarrow (\forall X1.(m3_glib_001 \\ X1 X0) \Rightarrow ((v1_glib_001 X1 X0) \Leftrightarrow (k1_funct_1 X1 np_1 = k1_funct_1 X1 \\ (k3_finseq_1 X1)))) \end{aligned}$$