

t36\_matrix\_4 (TM-  
SxYUo4S6y8YGB2V8wmejnyuKkRQgQA1ZU)

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Let  $v2\_struct\_0 : \iota \Rightarrow o$  be given. Let  $v6\_struct\_0 : \iota \Rightarrow o$  be given. Let  $v13\_algstr\_0 : \iota \Rightarrow o$  be given. Let  $v33\_algstr\_0 : \iota \Rightarrow o$  be given. Let  $v3\_group\_1 : \iota \Rightarrow o$  be given. Let  $v5\_group\_1 : \iota \Rightarrow o$  be given. Let  $v2\_rlvect\_1 : \iota \Rightarrow o$  be given. Let  $v3\_rlvect\_1 : \iota \Rightarrow o$  be given. Let  $v4\_rlvect\_1 : \iota \Rightarrow o$  be given. Let  $v4\_vectsp\_1 : \iota \Rightarrow o$  be given. Let  $v5\_vectsp\_1 : \iota \Rightarrow o$  be given. Let  $l6\_algstr\_0 : \iota \Rightarrow o$  be given. Let  $v1\_matrix\_1 : \iota \Rightarrow o$  be given. Let  $m2\_finseq\_1 : \iota \Rightarrow \iota \Rightarrow o$  be given. Let  $k3\_finseq\_2 : \iota \Rightarrow \iota$  be given. Let  $u1\_struct\_0 : \iota \Rightarrow \iota$  be given. Let  $k2\_matrix\_3 : \iota \Rightarrow \iota \Rightarrow \iota$  be given. Let  $k1\_matrix\_3 : \iota \Rightarrow \iota \Rightarrow \iota \Rightarrow \iota$  be given. Let  $k3\_finseq\_1 : \iota \Rightarrow \iota$  be given. Let  $k1\_matrix\_1 : \iota \Rightarrow \iota$  be given. Let  $k1\_matrix\_4 : \iota \Rightarrow \iota \Rightarrow \iota \Rightarrow \iota$  be given. Let  $k3\_matrix\_3 : \iota \Rightarrow \iota \Rightarrow \iota \Rightarrow \iota$  be given. Assume the following.

$$\begin{aligned} & \forall X0. ((\neg v2\_struct\_0 X0) \wedge ((\neg v6\_struct\_0 X0) \wedge ((v13\_algstr\_0 \\ & X0) \wedge ((v33\_algstr\_0 X0) \wedge ((v3\_group\_1 X0) \wedge ((v5\_group\_1 X0) \wedge \\ & (v2\_rlvect\_1 X0) \wedge ((v3\_rlvect\_1 X0) \wedge ((v4\_rlvect\_1 X0) \wedge ((v4\_vectsp\_1 \\ & X0) \wedge ((v5\_vectsp\_1 X0) \wedge (l6\_algstr\_0 X0)))))))))) \Rightarrow (\forall X1. \\ & ((v1\_matrix\_1 X1) \wedge (m2\_finseq\_1 X1 (k3\_finseq\_2 (u1\_struct\_0 \\ & X0)))) \Rightarrow (k1\_matrix\_4 X0 X1 X1 = k1\_matrix\_3 X0 (k3\_finseq\_1 X1) ( \\ & k1\_matrix\_1 X1))) \end{aligned} \tag{1}$$

Assume the following.

$$\begin{aligned} & \forall X0. ((\neg v2\_struct\_0 X0) \wedge ((\neg v6\_struct\_0 X0) \wedge ((v13\_algstr\_0 \\ & X0) \wedge ((v33\_algstr\_0 X0) \wedge ((v3\_group\_1 X0) \wedge ((v5\_group\_1 X0) \wedge \\ & (v2\_rlvect\_1 X0) \wedge ((v3\_rlvect\_1 X0) \wedge ((v4\_rlvect\_1 X0) \wedge ((v4\_vectsp\_1 \\ & X0) \wedge ((v5\_vectsp\_1 X0) \wedge (l6\_algstr\_0 X0)))))))))) \Rightarrow (\forall X1. \\ & ((v1\_matrix\_1 X1) \wedge (m2\_finseq\_1 X1 (k3\_finseq\_2 (u1\_struct\_0 \\ & X0)))) \Rightarrow (k3\_matrix\_3 X0 X1 (k2\_matrix\_3 X0 X1) = k1\_matrix\_3 X0 ( \\ & k3\_finseq\_1 X1) (k1\_matrix\_1 X1))) \end{aligned} \tag{2}$$

Assume the following.

$$\begin{aligned}
& \forall X0.((\neg v2\_struct\_0 X0) \wedge ((\neg v6\_struct\_0 X0) \wedge ((v13\_algstr\_0 \\
& X0) \wedge ((v33\_algstr\_0 X0) \wedge ((v3\_group\_1 X0) \wedge ((v5\_group\_1 X0) \wedge ( \\
& (v2\_rlvect\_1 X0) \wedge ((v3\_rlvect\_1 X0) \wedge ((v4\_rlvect\_1 X0) \wedge ((v4\_vectsp\_1 \\
& X0) \wedge ((v5\_vectsp\_1 X0) \wedge (l6\_algstr\_0 X0)))))))))) \Rightarrow (\forall X1. \\
& ((v1\_matrix\_1 X1) \wedge (m2\_finseq\_1 X1 (k3\_finseq\_2 (u1\_struct\_0 \\
& X0)))) \Rightarrow (\forall X2. ((v1\_matrix\_1 X2) \wedge (m2\_finseq\_1 X2 (k3\_finseq\_2 \\
& (u1\_struct\_0 X0)))) \Rightarrow (((k3\_finseq\_1 X1 = k3\_finseq\_1 X2) \wedge (k1\_matrix\_1 \\
& X1 = k1\_matrix\_1 X2)) \Rightarrow (X1 = k3\_matrix\_3 X0 X1 (k1\_matrix\_4 X0 X2 X2))))))
\end{aligned} \tag{3}$$

**Theorem 1**

$$\begin{aligned}
& \forall X0.((\neg v2\_struct\_0 X0) \wedge ((\neg v6\_struct\_0 X0) \wedge ((v13\_algstr\_0 \\
& X0) \wedge ((v33\_algstr\_0 X0) \wedge ((v3\_group\_1 X0) \wedge ((v5\_group\_1 X0) \wedge ( \\
& (v2\_rlvect\_1 X0) \wedge ((v3\_rlvect\_1 X0) \wedge ((v4\_rlvect\_1 X0) \wedge ((v4\_vectsp\_1 \\
& X0) \wedge ((v5\_vectsp\_1 X0) \wedge (l6\_algstr\_0 X0)))))))))) \Rightarrow (\forall X1. \\
& ((v1\_matrix\_1 X1) \wedge (m2\_finseq\_1 X1 (k3\_finseq\_2 (u1\_struct\_0 \\
& X0)))) \Rightarrow ((k2\_matrix\_3 X0 X1 = k1\_matrix\_3 X0 (k3\_finseq\_1 X1) (k1\_matrix\_1 \\
& X1)) \Rightarrow (X1 = k1\_matrix\_3 X0 (k3\_finseq\_1 X1) (k1\_matrix\_1 X1))))
\end{aligned}$$