

First-Order Instantiation-Based Tableau

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Outline

- ▶ Brief History: How did we get here?
- ▶ First-Order Tableau Rules for Satallax/Lash: Where are we?
 - ▶ Instantiation Based
 - ▶ No Free Variables, No Unification
 - ▶ What are the Rules for Equality?
- ▶ Tableau Is Sometimes Better Than Resolution:
Is it worth being here?
- ▶ Completeness: Are we really here?
- ▶ Alternative Rules: Where could we go from here?

Outline

History

Rules for Satallax/Lash

100 Problems

Completeness

Alternative Rules

Conclusion

A Little History

Beth, Hintikka, Smullyan, Fitting

$$\text{Rule A: } \frac{\alpha}{\alpha_1 \alpha_2} \qquad \text{Rule B: } \frac{\beta}{\beta_1 | \beta_2}$$

$$\text{Rule C: } \frac{\gamma}{\gamma(a)}, \text{ where } a \text{ is any parameter.}$$

$$\text{Rule D: } \frac{\delta}{\delta(a)}, \text{ where } a \text{ is a new parameter.}$$

Smullyan 1995 *First-Order Logic*

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Smullyan 1995 *First-Order Logic*

- ▶ Only parameters as terms
- ▶ No equality
- ▶ Is every new rule the “ ε -rule”?

Quick Higher-Order ATP History

Andrews, Huet

- ▶ Huet: Resolution, 1972
- ▶ Andrews: Several theoretical papers in the 1970s
- ▶ Leading to a system TPS started in the 1980s:
TPS (Andrews' Higher-Order "Theorem Proving System")
- ▶ Automation based on:
 - ▶ expansion proofs (like a compact sequent calculus) and
 - ▶ mating method/connection method (close to tableau)

Higher-Order Tableau History

Kohlhase (TABLEAUX 1995) *Higher-Order Tableaux*

Like Smullyan's but with "free variables" for universals:

$$\begin{array}{ccc} \frac{(\mathbf{A} \vee \mathbf{B})^T}{\mathbf{A}^T \mid \mathbf{B}^T} \mathcal{HT}(\wedge) & \frac{(\mathbf{A} \vee \mathbf{B})^F}{\mathbf{A}^F \mid \mathbf{B}^F} \mathcal{HT}(\vee) & \frac{(\neg \mathbf{A})^T}{\mathbf{A}^F} \mathcal{HT}(\neg^F) \quad \frac{(\neg \mathbf{A})^F}{\mathbf{A}^T} \mathcal{HT}(\neg^T) \\ & \frac{(\Pi^\alpha \mathbf{A})^T}{(\mathbf{A} X_\alpha^+)^T} \mathcal{HT}(all) & \frac{(\Pi^\alpha \mathbf{A})^F}{(\mathbf{A} X_\alpha^-)^F} \mathcal{HT}(ex) \end{array}$$

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$$\frac{(\Pi^\alpha \mathbf{A})^T}{(\mathbf{A} X_\alpha^+)^T} \mathcal{HT}(all) \quad \frac{(\Pi^\alpha \mathbf{A})^F}{(\mathbf{A} X_\alpha^-)^F} \mathcal{HT}(ex)$$

New "decomposition" rule:

$$\frac{h\bar{\mathbf{U}}^n \neq? h\bar{\mathbf{V}}^n \quad h \in \Sigma \cup \text{Dom}(\Gamma^0) \cup \text{Dom}(\Gamma^-)}{\mathbf{U}^1 \neq? \mathbf{V}^1 \mid \dots \mid \mathbf{U}^n \neq? \mathbf{V}^n} \mathcal{HT}(dec)$$

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And other rules...

Higher-Order Tableau History

Konrad (TPHOLs 1998) *HOT: A Concurrent Automated Theorem Prover Based on Higher-Order Tableaux*

Again...usual rules with “free variables” for universals:

$$\frac{\alpha}{\alpha_1 \mid \alpha_2} \textit{alpha} \quad \frac{\beta}{\beta_1 \mid \beta_2} \textit{beta} \quad \frac{\neg \mathbf{F}}{\mathbf{F}} \textit{not}$$
$$\frac{\delta}{\delta((sk^n X_1, \dots, X_n))} \textit{delta} \quad \frac{\gamma}{\gamma(V)} \textit{gamma}$$
$$\frac{h\overline{\mathbf{U}}^n \neq? h\overline{\mathbf{V}}^n}{\mathbf{U}^1 \neq? \mathbf{V}^1 \mid \dots \mid \mathbf{U}^n \neq? \mathbf{V}^n} \textit{dec}$$

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$$\frac{\delta}{\delta((sk^n X_1, \dots, X_n))} \textit{delta} \qquad \frac{\gamma}{\gamma(V)} \textit{gamma}$$

$$\frac{h\overline{\mathbf{U}}^n \neq? h\overline{\mathbf{V}}^n}{\mathbf{U}^1 \neq? \mathbf{V}^1 \mid \dots \mid \mathbf{U}^n \neq? \mathbf{V}^n} \textit{dec}$$

Plus “link” rules (like “general mating” rule):

$$\frac{\mathbf{A}_o \quad \mathbf{B}_o}{\neg \mathbf{A} \neq? \mathbf{B}} \textit{link}_1 \qquad \frac{\mathbf{A}_o \quad \mathbf{B}_o}{\mathbf{A} \neq? \neg \mathbf{B}} \textit{link}_2$$

Higher-Order Tableau History

Brown, Smolka (LMCS 2010) *Analytic Tableaux for Simple Type Theory and its First-Order Fragment*

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Decomposition rule:

$$\mathcal{T}_{\text{DEC}} \frac{x s_1 \dots s_n \neq_{\alpha} x t_1 \dots t_n}{s_1 \neq t_1 \mid \dots \mid s_n \neq t_n} \quad n \geq 0$$

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Mating rule (instead of Konrad's Link rules):

$$\mathcal{T}_{\text{MAT}} \frac{xs_1 \dots s_n, \neg xt_1 \dots t_n}{s_1 \neq t_1 \mid \dots \mid s_n \neq t_n} \quad n \geq 0$$

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Confrontation rule for positive equations:

$$\mathcal{T}_{\text{CON}} \frac{s =_{\alpha} t, u \neq_{\alpha} v}{s \neq u, t \neq u \mid s \neq v, t \neq v}$$

Flashback: Takahashi's Forgotten Extensionality Rule

Takahashi (Proc. Japan Acad. 1968) *Simple Type Theory of Genzten Style with the Inference of Extensionality*

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Almost a (sequent calculus) “mating” rule:

$$\frac{S_{1i_1} \cdots S_{1i_m} \quad S_{2i_1} \cdots S_{2i_m}}{(d_1^{\tau_1}, \dots, d_n^{\tau_n} \in e^{(\tau_1, \dots, \tau_n)}, \Gamma \rightarrow \Delta, (e_1^{\tau_1}, \dots, e_n^{\tau_n} \in e^{(\tau_1, \dots, \tau_n)}),$$

where

- 1) $e^{(\tau_1, \dots, \tau_n)}$ is a free variable or a constant;
- 2) at least one of τ_1, \dots, τ_n is $\neq 0$;
- 3) $\tau_i = 0$ implies $d_i^{\tau_i} = e_i^{\tau_i}$;
- 4) i_1, \dots, i_m are all the indices i with $\tau_i \neq 0$;
- 5) if $\tau_i = 1$, the S_{1i} and S_{2i} denote the sequents

$$d_i^{\tau_i}, \Gamma \rightarrow \Delta, e_i^{\tau_i}$$

$$e_i^{\tau_i}, \Gamma \rightarrow \Delta, d_i^{\tau_i}$$

respectively;

- 6) if $\tau_i = (\sigma_{i1}, \dots, \sigma_{ir})$, then S_{1i} and S_{2i} denote the sequents

$$(a_{i1}^{\sigma_{i1}}, \dots, a_{ir}^{\sigma_{ir}} \in d_i^{\tau_i}), \Gamma \rightarrow \Delta, (a_{i1}^{\sigma_{i1}}, \dots, a_{ir}^{\sigma_{ir}} \in e_i^{\tau_i}),$$

$$(a_{i1}^{\sigma_{i1}}, \dots, a_{ir}^{\sigma_{ir}} \in e_i^{\tau_i}), \Gamma \rightarrow \Delta, (a_{i1}^{\sigma_{i1}}, \dots, a_{ir}^{\sigma_{ir}} \in d_i^{\tau_i})$$

respectively ($a_{i1}^{\sigma_{i1}}, \dots, a_{ir}^{\sigma_{ir}}$ should not occur in the lower sequent of this inference).

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Rules for Satallax/Lash

100 Problems

Completeness

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Satallax/Lash

- ▶ Satallax: Higher-order ATP based on a Henkin complete tableau calculus.
- ▶ Won TH0 division of CASC most years of the 2010s.
- ▶ Instantiation based – used *no* unification in the basic calculus.
- ▶ Able to reason with equations without rewriting deeply inside terms.

- ▶ Lash is a new implementation of Satallax's calculus.
- ▶ Cezary Kaliszyk reimplemented terms/ $\beta\eta$ -normalization in C
- ▶ ...with perfect sharing.
- ▶ Lash is much faster than Satallax, but loses CASC.

Satallax/Lash First-Order Tableau

- ▶ A branch is a set of closed formulas.
- ▶ A branch is *closed* if either
 - ▶ φ and $\neg\varphi$ are on the branch for some φ , or
 - ▶ $s \neq s$ is on the branch for some s .
- ▶ A term t is *discriminating* for a branch if either $s \neq t$ or $t \neq s$ is on the branch (for some term s).

Satallax/Lash First-Order Tableau Rules (1)

Usual rules

$$\frac{\varphi \vee \psi}{\varphi | \psi} \quad \frac{\neg(\varphi \vee \psi)}{\neg\varphi, \neg\psi} \quad \frac{\neg\neg\varphi}{\varphi} \quad \frac{\forall x.\varphi(x)}{\varphi(t)} \text{ } t \text{ discriminating}$$
$$\frac{\neg\forall x.\varphi(x)}{\neg\varphi(c)} \text{ } c \text{ fresh}$$

Note: only use “discriminating” instantiations in \forall rule.

There are no free variables to be instantiated later.

Satallax/Lash First-Order Tableau Rules (2)

Other rules (involving disequations)

$$\text{Mating} \frac{p(s_1, \dots, s_n), \neg p(t_1, \dots, t_n)}{s_1 \neq t_1 \mid \dots \mid s_n \neq t_n}$$

$$\text{Dec} \frac{f(s_1, \dots, s_n) \neq f(t_1, \dots, t_n)}{s_1 \neq t_1 \mid \dots \mid s_n \neq t_n}$$

Satallax/Lash First-Order Tableau Rules (3)

Equality rule.

What it's *not*:

$$\text{Rewrite } \frac{s = t, \varphi[s]}{\varphi[t]}$$

Satallax/Lash First-Order Tableau Rules (3)

Equality rule.

What it's *not*:

$$\text{Rewrite } \frac{s = t, \varphi[s]}{\varphi[t]}$$

There is *no* rewrite rule in the calculus.

Satallax/Lash First-Order Tableau Rules (3)

Equality rule.

What it *is*:

$$\text{Con } \frac{s = t, u \neq v}{s \neq u, t \neq u \mid s \neq v, t \neq v}$$

Combining with a SAT Solver

- ▶ Both Satallax and Lash search by applying tableau rules, generating propositional clauses and incrementally sending the clauses to MiniSat.
- ▶ When the clauses are unsatisfiable, there is a tableau refutation.
- ▶ Details are here:

Brown (JAR 2013) Reducing Higher-Order Theorem Proving to a Sequence of SAT Problems

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Simple Clausal Problem Set

- ▶ 100 (first-order clausal) problems with similar format.
- ▶ All have 5 clauses.
- ▶ 2 Clauses (model must be infinite):
 - ▶ $\forall x.f(x) \neq c$
 - ▶ $\forall xy.f(x) \neq f(y) \vee x = y$
- ▶ 3 Clauses (model must be finite):
 - ▶ Third clause: $\forall xy.x = y \vee r(x, y) \vee b(x, y)$
 - ▶ Fourth clause: $\forall x_0 \dots x_n. \dots \neg r(x_i, x_j) \dots$
 - ▶ Fifth clause: $\forall x_0 \dots x_n. \dots \neg b(x_i, x_j) \dots$
- ▶ The last two clauses always have between 3 and 10 literals.

Simplest of the 100

1. $\forall x.f(x) \neq c$
2. $\forall xy.f(x) \neq f(y) \vee x = y$
3. Third clause: $\forall xy.x = y \vee r(x, y) \vee b(x, y)$
4. Fourth clause: $\forall x_0x_1x_2.\neg r(x_0, x_1) \vee \neg r(x_0, x_2) \vee \neg r(x_1, x_2)$
5. Fifth clause: $\forall x_0x_1x_2.\neg b(x_0, x_1) \vee \neg b(x_0, x_2) \vee \neg b(x_1, x_2)$

Sketch of Lash Search

- ▶ Start with the branch with the 5 formulas.
- ▶ Technically there are no discriminating terms, so seed instantiations with the constant c .
- ▶ Instantiate $\forall x.f(x) \neq c$ with c .
- ▶ Now $f(c) \neq c$ is on the branch and both $f(c)$ and c are discriminating.
- ▶ Instantiate all \forall 's with c and $f(c)$.
- ▶ This gives more discriminating terms and leads to the \forall formulas.
- ▶ Split the \forall 's and let MiniSat sort out unsatisfiability.
- ▶ Easiest of the 100 takes Lash < 50 ms.

Comparison on Problem Set

- ▶ 5 minute timeout
- ▶ Lash: 82

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- ▶ SATCOP: 56 (Michael Rawson)

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- ▶ Geo-III: 11 (Hans de Nivelles)
- ▶ iProver: 8 (Konstantin Korovin)
- ▶ Vampire: 3

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Completeness

- ▶ Suppose a branch A is not tableau refutable.
- ▶ A can be extended to a Hintikka set H .
- ▶ *Model Existence*: H has a model.
- ▶ The model construction follows ideas from Schütte 1960, Tait 1966, Takahashi 1967, Prawitz 1968, Takahashi 1968 and Andrews 1971.

Hintikka Set (1)

- ▶ $s \neq s \notin H$.
- ▶ $s \notin H$ or $\neg s \notin H$.
- ▶ If $\neg\neg\varphi \in H$, then $\varphi \in H$.
- ▶ If $\varphi \vee \psi \in H$, then $\varphi \in H$ or $\psi \in H$.
- ▶ If $\neg(\varphi \vee \psi) \in H$, then $\neg\varphi \in H$ and $\neg\psi \in H$.
- ▶ If $\forall x.\varphi(x) \in H$ and t discriminating on H , then $\varphi(t) \in H$.
- ▶ If $\neg\forall x.\varphi(x) \in H$, then $\varphi(t) \in H$ for some term t .

Hintikka Set (2)

- ▶ Assume signature just has c , f , r and b .
- ▶ (Dec) If $f(s) \neq f(t) \in H$, then $(s \neq t) \in H$.
- ▶ (Mat) If $r(s_1, s_2) \in H$ and $\neg r(t_1, t_2) \in H$, then $(s_1 \neq t_1) \in H$ or $(s_2 \neq t_2) \in H$.
- ▶ (Mat) If $b(s_1, s_2) \in H$ and $\neg b(t_1, t_2) \in H$, then $(s_1 \neq t_1) \in H$ or $(s_2 \neq t_2) \in H$.
- ▶ (Con) If $(s = t) \in H$ and $(u \neq v) \in H$, then $(s \neq u) \in H$ and $(t \neq u) \in H$
or $(s \neq v) \in H$ and $(t \neq v) \in H$.

Compatibility and Possible Values

- ▶ Terms s and t are *compatible* if $(s \neq t) \notin H$ and $(t \neq s) \notin H$.
- ▶ A *discriminant* Δ is a maximal set of compatible discriminating terms.
- ▶ Let D (domain of interpretation) be the set of all discriminants.
- ▶ Possible values: $s \triangleright \Delta$ means “ s has Δ as possible value.”
- ▶ Def: $s \triangleright \Delta$ if $s \in \Delta$ or s is not discriminating.
- ▶ Theorem: Every set of compatible terms has a common possible value.
- ▶ Theorem: If $s = t \in H$, then there is one Δ with $s \triangleright \Delta$ and also $t \triangleright \Delta$.

Possible Values For Terms

- ▶ Recall: D is the set of all discriminants.
- ▶ Let $g : D \rightarrow D$.
- ▶ Lift \triangleright to unary functions:
- ▶ Def: $f \triangleright g$ if $f(s) \triangleright g(\Delta)$ whenever $s \triangleright \Delta$.
- ▶ Thm: There is a g such that $f \triangleright g$.
- ▶ Interpretation of terms: interpret
 - ▶ c as Δ_c where $c \triangleright \Delta_c$ and
 - ▶ f by g where $f \triangleright g$.
- ▶ Induction: $\theta(s) \triangleright \llbracket s \rrbracket_\alpha$ if $\theta(x) \triangleright \alpha(x)$ for all x .
- ▶ If $(s \neq t) \in H$, then $\llbracket s \rrbracket \neq \llbracket t \rrbracket$.
- ▶ If $(s = t) \in H$, then $\llbracket s \rrbracket = \llbracket t \rrbracket$.

Possible Values For Formulas

- ▶ Recall: D is the set of all discriminants.
- ▶ Let 0 and 1 be possible values for formulas.
- ▶ Def:
 - ▶ $\varphi \triangleright 0$ if $\varphi \notin H$.
 - ▶ $\varphi \triangleright 1$ if $\neg\varphi \notin H$.
- ▶ Two formulas φ and ψ are compatible unless $\varphi \in H$ and $\neg\psi \in H$ or $\neg\varphi \in H$ and $\psi \in H$.
- ▶ Let $Q : D \times D \rightarrow \{0, 1\}$ and q be the relation symbol r or b .
- ▶ Def: $q \triangleright Q$ if $q(s, t) \triangleright Q(\Delta, \Delta')$ whenever $s \triangleright \Delta$ and $t \triangleright \Delta'$.
- ▶ Interpret r using R such that $r \triangleright R$ and b using B such that $b \triangleright B$.
- ▶ Theorem: This is a model of H .

Two Possible Values For Relations

- ▶ When choosing Q such that $q \triangleright Q$ there are two obvious choices:
- ▶ Minimum: $Q(\Delta, \Delta')$ holds if
$$q(s, t) \in H \text{ for some } s \in \Delta \text{ and } t \in \Delta'.$$
- ▶ Maximum: $Q(\Delta, \Delta')$ holds unless
$$\neg q(s, t) \in H \text{ for some } s \in \Delta \text{ and } t \in \Delta'.$$
- ▶ In the model existence proof above any choice works, but...

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Special Rule for Irreflexivity

- ▶ It is possible to avoid some \forall quantifiers by replacing a universally quantified formula with a rule.
- ▶ Example: $\forall x. \neg r(x, x)$.
- ▶ Incomplete approach: A is closed if $\neg r(s, s) \in H$.
- ▶ Instead consider this (complete) rule:

$$\text{Irref} \frac{r(s, t)}{s \neq t}$$

- ▶ Corresponding Hintikka condition:
- ▶ If $r(s, t) \in H$, then $(s \neq t) \in H$.
- ▶ If we choose minimum R with $r \triangleright R$, then $\forall x. \neg r(x, x)$ will hold.

Special Rule for Third Clause

- ▶ Rule replacing third clause: $\forall xy. x = y \vee r(x, y) \vee b(x, y)$

$$\text{Cover } \frac{\neg r(s, t)}{s = t | b(s, t)}$$

- ▶ Hintikka condition:
- ▶ If $\neg r(s, t) \in H$, then $s = t \in H$ or $b(s, t) \in H$.
- ▶ Choosing max R ensures third clause holds.

Special Rule for Last Clauses

- ▶ Rule replacing fourth or fifth clauses, e.g.,
 $\forall x_0 x_1 x_2. \neg b(x_0, x_1) \vee \neg b(x_0, x_2) \vee \neg b(x_1, x_2)$

$$\text{NotHom} \frac{b(s_1, t), b(s_2, u)}{s_1 \neq s_2 \mid \neg b(t, u)}$$

- ▶ Hintikka condition:
- ▶ If $b(s_1, t), b(s_2, u) \in H$, then $s_1 \neq s_2 \in H$ or $\neg b(t, u) \in H$.
- ▶ Choosing min B ensures clause holds.

Results with Special Rules

- ▶ Implemented optional use of special rules in Lash.
- ▶ Caveat: Restriction to only create rules if they're easy to apply.
- ▶ Result: Lash essentially proves the same 82.
- ▶ Some are faster and some are slower.
- ▶ E.G.: One that took just over 2 minutes before takes only 16 seconds with one kind of special rule, but not the other.

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- ▶ Completeness proof from related higher-order contexts (Takahashi 1967-1968, Prawitz 1968, Andrews 1971)

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- ▶ Set of problems where it outperforms resolution
- ▶ Completeness proof from related higher-order contexts (Takahashi 1967-1968, Prawitz 1968, Andrews 1971)
- ▶ Modifications to Completeness Proof justify lifting some formulas to rules

Final Slide

Thank you!

Questions?