

# A Finitely Axiomatizable Set Theory in Typed First-Order Logic\*

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**Abstract**

## 1 Introduction

## 2 Syntax

We work over a first-order logic with five types:  $\mathbf{M}$  (sets),  $\hat{\mathbf{M}}$  (generalized sets),  $\hat{\mathbf{P}}$  (generalized propositions),  $\mathbf{S}$  (substitutions) and  $\mathbf{A}$  (assignments). For each type  $T$ , let  $\mathcal{V}_T$  be an infinite set of variables of type  $T$ . We assume that if  $T \neq T'$ , then  $\mathcal{V}_T$  and  $\mathcal{V}_{T'}$  are disjoint. We will use  $x, y$  to range over variables and more specifically  $x^T$  to range over variables of type  $T$ .

We define the set of terms  $\mathcal{T}_T$  of type  $T$  by mutual recursion as follows:

$$\begin{aligned}
 (X, Y) \quad \mathcal{T}_{\mathbf{M}} &:= x^{\mathbf{M}} | \emptyset | \wp(X) | \bigcup(X) | v(U, \alpha) \\
 (\alpha, \beta) \quad \mathcal{T}_{\mathbf{A}} &:= x^{\mathbf{A}} | \mathbf{k}_{\emptyset} | (X \triangleright \alpha) | (\sigma \alpha) \\
 (\sigma, \tau) \quad \mathcal{T}_{\mathbf{S}} &:= x^{\mathbf{S}} | \text{id} | \uparrow | (U \cdot \sigma) | (\sigma \circ \tau) \\
 (U, V) \quad \mathcal{T}_{\hat{\mathbf{M}}} &:= x^{\hat{\mathbf{M}}} | \mathbf{k}(X) | 0 | U[\sigma] | \hat{\emptyset} | \hat{\wp}(U) | \hat{\bigcup}(U) | \{U\} | \in V; \Phi | \varepsilon(\Phi) \\
 (\Phi, \Psi) \quad \mathcal{T}_{\hat{\mathbf{P}}} &:= x^{\hat{\mathbf{P}}} | \Phi[\sigma] | (U \hat{\in} V) | (U \hat{=} V) | \hat{\perp} | (\Phi \hat{\rightarrow} \Psi) | (\hat{\forall} \Phi)
 \end{aligned}$$

We use  $s, t$  to range over terms over any type. Once we have the sets of typed terms, we define the set of formulas as follows:

$$(\varphi, \psi) \quad \text{formulas} \quad p(\Phi, \alpha) | s =_T t | X \in Y | \perp | (\varphi \rightarrow \psi) | \forall x. \phi \quad \text{where } s, t \in \mathcal{T}_T$$

We write  $\neg\varphi$  for  $\varphi \rightarrow \perp$ ,  $\varphi \vee \psi$  for  $\neg\varphi \rightarrow \psi$ ,  $\varphi \wedge \psi$  for  $\neg(\varphi \rightarrow \neg\psi)$ ,  $\varphi \leftrightarrow \psi$  for  $(\varphi \rightarrow \psi) \wedge (\psi \rightarrow \varphi)$ , and  $\exists x. \varphi$  for  $\neg\forall x. \neg\varphi$ .

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$$\begin{aligned}
& (\forall x^M. x^M \in X \rightarrow x^M \in Y) \rightarrow (\forall x^M. x^M \in Y \rightarrow x^M \in X) \rightarrow X = Y \quad \neg(X \in \emptyset) \\
& (X \in \wp(Y)) \leftrightarrow (\forall x^M. x^M \in X \rightarrow x^M \in Y) \\
& (X \in \bigcup(Y)) \leftrightarrow (\exists x^M. x^M \in Y \wedge X \in x^M) \\
& (X \in v(\{U|. \in V; \Phi\}, \alpha) \leftrightarrow (\exists x^M. x^M \in v(V, \alpha) \wedge X = v(U, x^M \triangleright \alpha) \wedge p(\Phi, x^M \triangleright \alpha)) \\
& p(\Phi, X \triangleright \alpha) \rightarrow p(\Phi, \varepsilon(\Phi) \triangleright \alpha) \quad \textit{infinity?}
\end{aligned}$$

Figure 1: Set Theoretic Axioms

$$\begin{aligned}
& \hat{\perp}[\sigma] = \hat{\perp} \quad (\Phi \dot{\rightarrow} \Psi)[\sigma] = (\Phi[\sigma] \dot{\rightarrow} \Psi[\sigma]) \quad (\hat{v}\Phi)[\sigma] = (\hat{v}\Phi[0 \cdot (\sigma \circ \uparrow)]) \\
& (U \hat{=} V)[\sigma] = (U[\sigma] \hat{=} V[\sigma]) \quad (U \hat{\in} V)[\sigma] = (U[\sigma] \hat{\in} V[\sigma]) \\
& \varepsilon(U)[\sigma] = \varepsilon(U[0 \cdot (\sigma \circ \uparrow)]) \quad \hat{\emptyset}[\sigma] = \hat{\emptyset} \quad \hat{\wp}(U)[\sigma] = \hat{\wp}(U[\sigma]) \\
& \hat{\bigcup}(U)[\sigma] = \hat{\bigcup}(U[\sigma]) \quad \{U|. \in V; \Phi\}[\sigma] = \{U[0 \cdot (\sigma \circ \uparrow)]. \in V[\sigma]; \Phi[0 \cdot (\sigma \circ \uparrow)]\} \\
& U[\text{id}] = U \quad \Phi[\text{id}] = \Phi \quad 0[(U \cdot \sigma)] = U \quad U[\sigma][\tau] = U[\sigma \circ \tau] \\
& \Phi[\sigma][\tau] = \Phi[\sigma \circ \tau] \quad \text{id} \circ \sigma = \sigma \quad \sigma \circ \text{id} = \sigma \quad \uparrow \circ (U \cdot \sigma) = \sigma \\
& (U \cdot \sigma) \circ \tau = U[\tau] \circ (\sigma \circ \tau) \quad (\sigma_1 \circ \sigma_2) \circ \sigma_3 = \sigma_1 \circ (\sigma_2 \circ \sigma_3) \quad v(\mathbf{k}(X), \alpha) = X \\
& v(U[\sigma], \alpha) = v(U, (\sigma\alpha)) \quad \text{id}\alpha = \alpha \quad v(0, (X \triangleright \alpha)) = X \\
& (U \cdot \sigma)\alpha = v(U, \alpha) \triangleright (\sigma\alpha) \quad (\sigma \circ \tau)\alpha = \sigma(\tau\alpha) \quad v(\hat{\emptyset}, \alpha) = \emptyset \\
& v(\hat{\wp}(U), \alpha) = \wp(v(U, \alpha)) \quad v(\hat{\bigcup}(U), \alpha) = \bigcup(v(U, \alpha)) \\
& p(\Phi[\sigma], \alpha) \leftrightarrow p(\Phi, (\sigma\alpha)) \quad p(U \hat{\in} V, \alpha) \leftrightarrow v(U, \alpha) \in v(V, \alpha) \\
& p(U \hat{=} V, \alpha) \leftrightarrow v(U, \alpha) = v(V, \alpha) \quad \neg p(\hat{\perp}, \alpha) \\
& p(\Phi \dot{\rightarrow} \Psi, \alpha) \leftrightarrow (p(\Phi, \alpha) \rightarrow p(\Psi, \alpha)) \quad p(\hat{v}\Phi, \alpha) \leftrightarrow \forall x^M. p(\Phi, (x^M \triangleright \alpha))
\end{aligned}$$

Figure 2: Axioms for substitutions and assignments

### 3 Interpretations

When  $g : A \rightarrow B$  and  $f : B \rightarrow C$  we will use  $f \circ g$  to denote the usual composition of functions, as given by  $(f \circ g)(a) = f(g(a))$ . Let  $A$  be a set. We use  $\text{Id}_A$  to denote the identity function from  $A$  to  $A$ , omitting the subscript when it is clear in context. Likewise, we let  $\uparrow_A$  denote the function from  $A^\omega$  to  $A^\omega$  given by  $\uparrow_A(f)(n) = f(n+1)$ , omitting the subscript  $A$  when it is clear in context. Given an element  $a \in A$  and function  $f \in A^\omega$ , we write  $(a \blacktriangleright f)$  for the function from  $\omega$  to  $A$  given by  $(a \blacktriangleright f)(0) = a$  and  $(a \blacktriangleright f)(n+1) = f(n)$ . This will serve as the intended interpretation of the  $\triangleright$  operation for assignments. Given functions  $g : A^\omega \rightarrow A$  and  $h : A^\omega \rightarrow A^\omega$ , we write  $(g \odot h)$  for the function from  $A^\omega$  to  $A^\omega$  given by  $(g \odot h)(f)(0) = g(f)$  and  $(g \odot h)(f)(n+1) = h(f)(n)$ . This will serve as the intended interpretation of the  $\odot$  operation for substitutions.

An interpretation of the set theory is given by taking five nonempty sets  $\mathcal{D}_T$  for  $T \in \{\mathbf{M}, \mathbf{A}, \mathbf{S}, \hat{\mathbf{M}}, \hat{\mathbf{P}}\}$  and interpretations of the basic operators. We will further require the following:

- $\mathcal{D}_\mathbf{M}$  is a model of ZFC, where we also use  $\in$ ,  $\emptyset$ ,  $\wp$  and  $\bigcup$  to refer to the corresponding semantic notions in this model.
- There is a global choice operator  $\bar{\varepsilon} : \wp(\mathcal{D}_\mathbf{M}) \rightarrow \mathcal{D}_\mathbf{M}$  where  $\bar{\varepsilon}(\emptyset) = \emptyset$  and  $\bar{\varepsilon}(u) \in u$  for each nonempty  $u \subseteq \mathcal{D}_\mathbf{M}$
- $\mathcal{D}_\mathbf{A} \subseteq (\mathcal{D}_\mathbf{M})^\omega$ .
- $\mathcal{D}_\mathbf{S} \subseteq (\mathcal{D}_\mathbf{A})^{\mathcal{D}_\mathbf{A}}$ .
- $\mathcal{D}_{\hat{\mathbf{M}}} \subseteq (\mathcal{D}_\mathbf{M})^{\mathcal{D}_\mathbf{A}}$ .
- $\mathcal{D}_{\hat{\mathbf{P}}} \subseteq 2^{\mathcal{D}_\mathbf{A}}$ .
- $\text{Id} \in \mathcal{D}_\mathbf{S}$ ,  $\uparrow \in \mathcal{D}_\mathbf{S}$  and  $\mathcal{D}_\mathbf{S}$  is closed under composition.
- For  $X \in \mathcal{D}_\mathbf{M}$  and  $\alpha \in \mathcal{D}_\mathbf{A}$ ,  $(X \blacktriangleright \alpha) \in \mathcal{D}_\mathbf{A}$ .
- For  $U \in \mathcal{D}_{\hat{\mathbf{M}}}$  and  $\sigma \in \mathcal{D}_\mathbf{S}$ ,  $(U \odot \sigma) \in \mathcal{D}_\mathbf{S}$ .

Given these restrictions, it is easy to define an evaluation function  $\llbracket - \rrbracket_\nu$  for terms by recursion. The evaluation is relative to an environment  $\nu : \bigcup_T \mathcal{V}_T \rightarrow \bigcup_T \mathcal{D}_T$  where  $\phi(x) \in \mathcal{D}_T$  for each  $x \in \mathcal{V}_T$  and each type  $T$ . The definition is given in Figure 3.

We can now define validity of a formula in such an interpretation in the obvious manner.

- $\models_\nu p(\Phi, \alpha)$  if  $\llbracket \Phi \rrbracket_\nu(\llbracket \alpha \rrbracket_\nu) = 1$ .
- $\models_\nu s =_T t$  if  $\llbracket s \rrbracket_\nu = \llbracket t \rrbracket_\nu$ .
- $\not\models_\nu \perp$ .
- $\models_\nu (\phi \rightarrow \psi)$  if either  $\not\models_\nu \phi$  or  $\models_\nu \psi$ .
- For  $x \in \mathcal{V}_T$   $\models_\nu (\forall x. \phi)$  if  $\models_{\nu, x:=v} \phi$  for every  $v \in \mathcal{D}_T$  where  $\nu, x := v$  is the environment agreeing with  $\nu$  except sending  $x$  to  $v$ .

$$\begin{aligned}
\llbracket x \rrbracket_\nu &= \nu(x) & \llbracket \emptyset \rrbracket_\nu &= \emptyset & \llbracket \wp(X) \rrbracket_\nu &= \wp(\llbracket X \rrbracket_\nu) & \llbracket \bigcup(X) \rrbracket_\nu &= \bigcup(\llbracket X \rrbracket_\nu) \\
\llbracket v(U, \alpha) \rrbracket_\nu &= \llbracket U \rrbracket_\nu(\llbracket \alpha \rrbracket_\nu) & \llbracket \mathbf{k}_\emptyset \rrbracket_\nu(\gamma) &= \emptyset & \llbracket (X \triangleright \alpha) \rrbracket_\nu &= \llbracket X \rrbracket_\nu \blacktriangleright \llbracket \alpha \rrbracket_\nu \\
\llbracket (\sigma \alpha) \rrbracket_\nu &= \llbracket \sigma \rrbracket_\nu(\llbracket \alpha \rrbracket_\nu) & \llbracket \text{id} \rrbracket_\nu &= \text{id} & \llbracket \uparrow \rrbracket_\nu &= \uparrow & \llbracket (U \cdot \sigma) \rrbracket_\nu &= \llbracket U \rrbracket_\nu \circ \llbracket \sigma \rrbracket_\nu \\
\llbracket (\sigma \circ \tau) \rrbracket_\nu &= \llbracket \sigma \rrbracket_\nu \circ \llbracket \tau \rrbracket_\nu & \llbracket \mathbf{k}(X) \rrbracket_\nu(\gamma) &= \llbracket X \rrbracket_\nu & \llbracket 0 \rrbracket_\nu(\gamma) &= \gamma(0) \\
\llbracket U[\sigma] \rrbracket_\nu(\gamma) &= \llbracket U \rrbracket_\nu(\llbracket \sigma \rrbracket_\nu(\gamma)) & \llbracket \hat{\emptyset} \rrbracket_\nu(\gamma) &= \emptyset & \llbracket \hat{\wp}(U) \rrbracket_\nu(\gamma) &= \wp(\llbracket U \rrbracket_\nu(\gamma)) \\
\llbracket \hat{\bigcup}(U) \rrbracket_\nu(\gamma) &= \bigcup(\llbracket U \rrbracket_\nu(\gamma))
\end{aligned}$$

$$\llbracket \{U \mid \cdot \in V; \Phi\} \rrbracket_\nu(\gamma) = \{\llbracket U \rrbracket_\nu(v \blacktriangleright \gamma) \mid v \in \llbracket V \rrbracket_\nu(\gamma) \text{ where } \llbracket \Phi \rrbracket_\nu(v \blacktriangleright \gamma)\}$$

$$\llbracket \varepsilon(\Phi) \rrbracket_\nu(\gamma) = \bar{\varepsilon}\{v \in \mathcal{D}_M \mid \llbracket \Phi \rrbracket_\nu(v \blacktriangleright \gamma)\} \quad \llbracket \Phi[\sigma] \rrbracket_\nu(\gamma) = \llbracket \Phi \rrbracket_\nu(\llbracket \sigma \rrbracket_\nu(\gamma))$$

$$\llbracket U \hat{\in} V \rrbracket_\nu(\gamma) = \begin{cases} 1 & \text{if } \llbracket U \rrbracket_\nu(\gamma) \in \llbracket V \rrbracket_\nu(\gamma) \\ 0 & \text{otherwise} \end{cases}$$

$$\llbracket U \hat{=} V \rrbracket_\nu(\gamma) = \begin{cases} 1 & \text{if } \llbracket U \rrbracket_\nu(\gamma) = \llbracket V \rrbracket_\nu(\gamma) \\ 0 & \text{otherwise} \end{cases} \quad \llbracket \hat{1} \rrbracket_\nu(\gamma) = 0$$

$$\llbracket (\Phi \hat{\rightarrow} \Psi) \rrbracket_\nu(\gamma) = \begin{cases} 1 & \text{if } \llbracket \Phi \rrbracket_\nu(\gamma) = 0 \text{ or } \llbracket \Psi \rrbracket_\nu(\gamma) = 1 \\ 0 & \text{otherwise} \end{cases}$$

$$\llbracket (\hat{\forall} \Phi) \rrbracket_\nu(\gamma) = \begin{cases} 1 & \text{if } \llbracket \Phi \rrbracket_\nu(v \blacktriangleright \gamma) = 1 \text{ for every } v \in \mathcal{D}_M \\ 0 & \text{otherwise} \end{cases}$$

## 4 Examples

Consider the informal proposition  $\forall XYz.z \in \{x \in X|x \in Y\} \leftrightarrow z \in X \wedge z \in Y$ . To represent this as a formula, we must find a way to represent the term  $\{x \in X|x \in Y\}$ . If we reconsider  $\{x \in X|x \in Y\}$  as  $\{x|x \in X;x \in Y\}$ , then we can use the generalized set construct  $\{U|. \in V; \Phi\}$  where the de Bruijn variable 0 will play the role of the bound variable. The sets  $X$  and  $Y$  will need to be lifted via  $k$  to be generalized sets in order use them in this context, giving the term  $\{0|. \in k(X); 0 \in k(Y)\}$ . In order to use this term as a set, we must evaluate it using some assignment  $\alpha$ . In this case we simply use the assignment  $k_\emptyset$ . A formula corresponding to the original proposition is given by

$$\forall XYz.z \in v(\{0|. \in k(X); 0 \in k(Y)\}, k_\emptyset) \leftrightarrow z \in X \wedge z \in Y$$

where  $X, Y, z \in \mathcal{V}_M$ .